

Kuka Krc2 Programming Manual

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RoboDK supports all KUKA robot controllers since KRC2, including KUKA KRC3 and KRC4 controllers. This documentation is based on a KRC4 controller. The KRC4 robot controller runs the Microsoft Embedded Windows 7 operating system. Previous controllers, such as KRC2, run Windows 95. The robot teach pendant shows an "HMI" which is a program that KUKA developed to run on Windows and it is the ...

KUKA robots - RoboDK Documentation

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The choice of communication protocol between the PLC controller and the peripheral device most often depends on the main device, i.e. usually the PLC controller. Of course, it is not always possible, then various types of converters come into play, but this is a separate topic. In other words, we choose what we know and [...]

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